

Isidori I., Example 1.6.4

■ System of PDE (cannot be solved in a such way)

```
In[176]:= Clear[gradu]
gradu = Grad[u[x, y, z, t], {x, y, z, t}]
DSolve[{gradu.{1, 0, 0, y} == 0, gradu.{0, 1, 0, x} == 0}, u[x, y, z, t], {x, y, z, t}]
```

$$\text{Out[177]} = \left\{ u^{(1,0,0,0)}[x, y, z, t], u^{(0,1,0,0)}[x, y, z, t], u^{(0,0,1,0)}[x, y, z, t], u^{(0,0,0,1)}[x, y, z, t] \right\}$$

```
Out[178]:= DSolve[{y u^{(0,0,0,1)}[x, y, z, t] + u^{(1,0,0,0)}[x, y, z, t] == 0,
x u^{(0,0,0,1)}[x, y, z, t] + u^{(0,1,0,0)}[x, y, z, t] == 0}, u[x, y, z, t], {x, y, z, t}]
```

Unfortunately, this cannot be solved

■ PDE of the system can be solved one by one

```
In[198]:= ClearAll[x, u, gradu]
gradu = Grad[u[x, y, z, t], {x, y, z, t}];
```

```
In[200]:= g1 = {1, 0, 0, y};
g2 = {0, 1, 0, x};
```

```
In[202]:= DSolve[gradu.g1 == 0, u[x, y, z, t], {x, y, z, t}]
```

$$\text{Out[202]} = \left\{ \left\{ u[x, y, z, t] \rightarrow C[1][y, z][t - xy] \right\} \right\}$$

The solution ($C[1][y, z][t - xy]$) of the first equation can be interpreted as a function of y, z and of $t - xy$.
For example:

```
In[212]:= u = (Sin[y z] + z) (t - x y);
Simplify[Grad[u, {x, y, z, t}].g1]
```

$$\text{Out[213]} = 0$$

```
In[218]:= u = (Sin[y z] + z) Sin[(t - x y) z + y];
Simplify[Grad[u, {x, y, z, t}].g1]
```

$$\text{Out[219]} = 0$$

```
DSolve[gradu.g2 == 0, u[x, y, z, t], {x, y, z, t}]
```


$$\left\{ \left\{ u[x, y, z, t] \rightarrow C[1][x, z][t - xy] \right\} \right\}$$

From these solutions we can give a common solution.

Some examples: $u_1(x) = x_4 - x_1 x_2$, $u_2(x) = x_3$

Isidori I., Example 4.1.4

```
In[224]:= ClearAll[x, g, u]
x = {x1, x2, x3};
g = {Exp[x2], 1, 0};
gradu = Grad[u[x1, x2, x3], x];
DSolve[gradu.g == 0, u[x1, x2, x3], x]
```

 **Solve:** Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information.

```
Out[228]= {{u[x1, x2, x3] -> C[1][x3] [e^x2 - x1]}}
```

A solution for the PDE can be: $u(x) = e^{x_2} - x_1 + C(x_3)$

Example 1 (a)

```
In[229]:= x = {x1, x2, x3};
g = {0, 1, Sin[x1]};
gradu = Grad[u[x1, x2, x3], x];
DSolve[gradu.g == 0, u[x1, x2, x3], x]
Out[232]= {{u[x1, x2, x3] -> C[1] [x1] [x3 - x2 Sin[x1]]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (b)

```
x = {x1, x2, x3};
g = {0, 0, x2/(x1 + 1)};
gradu = Grad[u[x1, x2, x3], x];
DSolve[gradu.g == 0, u[x1, x2, x3], x]
{{u[x1, x2, x3] -> C[1] [x1, x2]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (c)

```
x = {x1, x2, x3, x4};
g = {1/(x4 + 1), 0, x2/(x4 + 1), 0};
gradu = Grad[u[x1, x2, x3, x4], x];
DSolve[gradu.g == 0, u[x1, x2, x3, x4], x]
{{u[x1, x2, x3, x4] -> C[1] [x2, x4] [-x1 x2 + x3]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (d)

```
In[65]:= x = {x1, x2, x3, x4};
g = {1, 0, Exp[x4] - 1, 0};
gradu = Grad[u[x1, x2, x3, x4], x];
DSolve[gradu.g == 0, u[x1, x2, x3, x4], x]
Out[68]= {{u[x1, x2, x3, x4] -> C[1] [x2, x4] [x1 - e^x4 x1 + x3]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (e)

```
In[111]:= x = {x1, x2, x3, x4};
g = {0, ArcTan[x3], 0, x1 ArcTan[x3]};
gradu = Grad[u[x1, x2, x3, x4], x];
DSolve[gradu.g == 0, u[x1, x2, x3, x4], x]
Out[114]= {{u[x1, x2, x3, x4] -> C[1] [x1, x3] [-x1 x2 + x4]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (f)

```
x = {x1, x2, x3, x4};
g = {0, ArcTan[x3], 0, x1 ArcTan[x3]};
gradu = Grad[u[x1, x2, x3, x4], x];
DSolve[gradu.g == 0, u[x1, x2, x3, x4], x]
{{u[x1, x2, x3, x4] -> C[1] [x1, x3] [-x1 x2 + x4]}}
```

From this output you can give a function(s) $\phi_i(x)$ such that $L_g \phi_i(x) = 0$.

Example 1 (g), continuous fermenter

```
In[317]:= μ =  $\frac{x2}{K2 x2^2 + x2 + K1}$ ;
x = {x1, x2};
h = x2;
f = {μ x1, - $\frac{\mu x1}{Y}$ }
Out[320]= { $\frac{x1 x2}{K1 + x2 + K2 x2^2}$ , - $\frac{x1 x2}{(K1 + x2 + K2 x2^2) Y}$ }

In[321]:= g = {- $\frac{x1}{V}$ ,  $\frac{Sf - x2}{V}$ };
gradu = Grad[u[x1, x2], x];
DSolve[gradu.g == 0, u[x1, x2], x]
Out[323]= {{u[x1, x2] -> C[1] [ $\frac{-Sf + x2}{x1}$ ]}}
```

Example 1 (h)

```
x = {x1, x2, x3, x4};
```

```

f = {x1 x2 - x13, x1, -x3, x12 + x2};
g = {0, 2 + 2 x3, 1, 0};
h = x4;
gradu = Grad[u[x1, x2, x3, x4], x];
DSolve[gradu.g == 0, u[x1, x2, x3, x4], x]

```

$$\left\{ \left\{ u[x1, x2, x3, x4] \rightarrow C[1][x1, x4] \left[\frac{1}{2} (-x2 + 2 x3 + x3^2) \right] \right\} \right\}$$

Example 1 (i)

```

In[390]:= x = {x1, x2, x3};
z = {z1, z2, z3};
f = {0, x1 + x22, x1 - x2};
g = {Exp[x2], Exp[x2], 0};
h = x3;
gradu = Grad[u[x1, x2, x3], x];
eqn = gradu.g == 0;
DSolve[eqn, u[x1, x2, x3], x]

```

```

Out[397]= { { u[x1, x2, x3] → C[1][x3] [-x1 + x2] } }

```

Example 1 (j)

```

In[374]:= x = {x1, x2, x3};
z = {z1, z2, z3};
f = {x3 (1 + x2), x1, x2 (1 + x1)};
g = {0, 1 + x2, -x3};
h = x1;
gradu = Grad[u[x1, x2, x3], x];
eqn = gradu.g == 0;
DSolve[eqn, u[x1, x2, x3], x]

```

```

Out[381]= { { u[x1, x2, x3] → C[1][x1] [(1 + x2) x3] } }

```

Example 2 (a), Controllability from LTI

```

In[424]:= x = {x1, x2, x3};
z = {z1, z2, z3};

f =  $\begin{pmatrix} -x3 \cos[x1]^2 \\ -x2 + x3 \\ x2 - 2 x3 + 2 \tan[x1] \end{pmatrix};$ 

g =  $\begin{pmatrix} \cos[x1]^2 \\ 1 \\ 2 \end{pmatrix};$ 

adfg = Simplify[Grad[g, x].f - Grad[f, x].g];
adffg = Simplify[Grad[adfg, x].f - Grad[f, x].adfg];

In[434]:= gradu = Grad[u[x1, x2, x3], x];
DSolve[(gradu.g)[[1]] == 0, u[x1, x2, x3], x]
DSolve[(gradu.adfg)[[1]] == 0, u[x1, x2, x3], x]
DSolve[(gradu.adffg)[[1]] == 0, u[x1, x2, x3], x]

Out[435]= {{u[x1, x2, x3] → C[1] [x3 - 2 Tan[x1], x2 - Tan[x1]]}}

Out[436]= {{u[x1, x2, x3] → C[1] [ $\frac{1}{2} (2 x3 - \tan[x1])$ ,  $\frac{1}{2} (2 x2 + \tan[x1])$ ]}},

Out[437]= {{u[x1, x2, x3] → C[1] [x3 + Tan[x1], x2 + 2 Tan[x1]]}}

```

Example 2 (b), Controllability from LTI

```

In[497]:= x = {x1, x2, x3};
z = {z1, z2, z3};

f =  $\begin{pmatrix} \frac{-2 x1^2 + 2 x3 + x1 (-2 + x2 + 2 x3)}{2 + x2 + x3} \\ \frac{-2 x2 + x1 (2 + x3)}{2 + x1} \\ -x2 - x3 \end{pmatrix};$ 

g =  $\begin{pmatrix} \frac{2 (2 + x1)}{2 + x2 + x3} \\ 1 \\ 1 \end{pmatrix};$ 

adfg = Simplify[Grad[g, x].f - Grad[f, x].g];
adffg = Simplify[Grad[adfg, x].f - Grad[f, x].adfg];

```

```

In[503]:= gradu = Grad[u[x1, x2, x3], x];
DSolve[(gradu.g)[[1]] == 0, u[x1, x2, x3], x]
DSolve[(gradu.adfg)[[1]] == 0, u[x1, x2, x3], x]
DSolve[(gradu.adffg)[[1]] == 0, u[x1, x2, x3], x]

Out[504]= {{u[x1, x2, x3] -> C[1] [- $\frac{-2 - x2 - x3}{2(2 + x1)}$ , - $\frac{-4 - 4x2 - x1x2 + x1x3}{2(2 + x1)}$ ]}]}

Out[505]= {{u[x1, x2, x3] -> C[1] [- $\frac{2 + x2 + x3}{2 + x1}$ , - $\frac{4 - 2x2 - 2x1x2 - x1x3}{2 + x1}$ ]}]}

Out[506]= {{u[x1, x2, x3] -> C[1] [- $\frac{2(2 + x2 + x3)}{2 + x1}$ , - $\frac{-8 - 2x2 + x1x2 + 2x1x3}{2 + x1}$ ]}]}

```

Example 3, Controllable manifold, fed-batch fermenter

$$\mu = \frac{x2}{K2 x2^2 + x2 + K1};$$

$$x = \{x1, x2, x3\};$$

$$h = S;$$

$$f = \left\{ \mu x1, -\frac{\mu x1}{Y}, 0 \right\}$$

$$g = \left\{ -\frac{x1}{x3}, \frac{Sf - x2}{x3}, 1 \right\}$$

$$\left\{ \frac{x1 x2}{K1 + x2 + K2 x2^2}, -\frac{x1 x2}{(K1 + x2 + K2 x2^2) Y}, 0 \right\}$$

$$\left\{ -\frac{x1}{x3}, \frac{Sf - x2}{x3}, 1 \right\}$$

$$\text{adfg} = \text{Simplify}[\text{Grad}[g, x] \cdot f - \text{Grad}[f, x] \cdot g];$$

$$\text{adfg} // \text{MatrixForm}$$

$$\begin{pmatrix} \frac{x1 (Sf - x2) (-K1 + K2 x2^2)}{(K1 + x2 + K2 x2^2)^2 x3} \\ -\frac{x1 (Sf - x2) (-K1 + K2 x2^2)}{(K1 + x2 + K2 x2^2)^2 x3 Y} \\ 0 \end{pmatrix}$$

$$\text{adffg} = \text{Simplify}[\text{Grad}[\text{adfg}, x] \cdot f - \text{Grad}[f, x] \cdot \text{adfg}];$$

$$\text{adffg} // \text{MatrixForm}$$

$$\begin{pmatrix} -\frac{x1^2 (K1^2 Sf - K2 (1 + K2 Sf) x2^4 - K1 x2 (-2 Sf + x2 - 4 K2 Sf x2 + 4 K2 x2^2))}{(K1 + x2 + K2 x2^2)^4 x3 Y} \\ \frac{x1^2 (K1^2 Sf - K2 (1 + K2 Sf) x2^4 - K1 x2 (-2 Sf + x2 - 4 K2 Sf x2 + 4 K2 x2^2))}{(K1 + x2 + K2 x2^2)^4 x3 Y^2} \\ 0 \end{pmatrix}$$

```

gradu = Grad[u[x1, x2, x3], x];
DSolve[gradu.g == 0, u[x1, x2, x3], x]
DSolve[gradu.adfg == 0, u[x1, x2, x3], x]
DSolve[gradu.adffg == 0, u[x1, x2, x3], x]

{{u[x1, x2, x3] -> C[1] [-Sf + x2/x1, x1 x3]}}

{{u[x1, x2, x3] -> C[1] [x3] [x1 + x2 Y/Y]}}

{{u[x1, x2, x3] -> C[1] [x3] [x1 + x2 Y/Y]}}

```

We try to find a common solution for the three different PDE:

```

Expand[(-Sf + x2/x1 + 1/Y) * x1 x3]

-Sf x3 + x2 x3 + x1 x3/Y

Expand[(x1 + x2 Y/Y - Sf) * x3]

-Sf x3 + x2 x3 + x1 x3/Y

Solve[-Sf x3 + x2 x3 + x1 x3/Y == a, x3]

{{x3 -> a Y/(x1 - Sf Y + x2 Y)}}

```



```
Plot3D[ $\frac{a Y}{x_1 - S f Y + x_2 Y}$  /. {a → -4, Y → 0.5, Sf → 10},
{x1, 0, 4}, {x2, 0, 4}, PlotRange → {{0, 4}, {0, 4}, {0, 35}}]
```

